

Lecture 7: Eigenvalues & Eigenvectors

- Unlike the system $\mathbf{Ax} = \mathbf{b}$ which has the single unknown vector \mathbf{x} , eigenvalue problems are of the form $\mathbf{Ax} = \lambda\mathbf{x}$, with unknowns \mathbf{x} and λ .
- The values of λ are known as the eigenvalues and the corresponding \mathbf{x} are the eigenvectors.
- Eigenvalue problems often arise from differential equations.

- Consider the example of a linear set of coupled differential equations:

$$\frac{dy}{dt} = \mathbf{A}y \quad (1)$$

- Inserting the solution $y = \mathbf{x}e^{(\lambda t)}$
- Results in: $\mathbf{A}\mathbf{x} = \lambda\mathbf{x}$
- Once the system is solved for all N linearly independent solution eigenvectors \mathbf{x} and corresponding λ 's for the $N \times N$ matrix \mathbf{A}
- The solution of the ODE is

$$y = c_1\mathbf{x}_1e^{(\lambda_1 t)} + c_2\mathbf{x}_2e^{(\lambda_2 t)} + \dots + c_N\mathbf{x}_Ne^{(\lambda_N t)}$$

- How to find these eigenvalues and eigenvectors?

```
% Get the eigenvalues of a matrix A
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```
% in MATLAB
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```
eig(A)
```

```
help eig
```

```
% To obtain diagonal matrix D of
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```
% eigenvalues, and a full matrix V
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```
% whose columns are the corresponding
```

```
% eigenvectors
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```
[V,D] = eig(A)
```

- Understanding eigenvalues and eigenvectors?
- Rewrite the eigenvalue problem $\mathbf{Ax} = \lambda\mathbf{x}$
 - $\Rightarrow \mathbf{Ax} = \mathbf{I}\lambda\mathbf{x}$ where \mathbf{I} is the identity matrix.
 - $\Rightarrow \mathbf{Ax} - \mathbf{I}\lambda\mathbf{x} = \mathbf{0}$
 - $\Rightarrow (\mathbf{A} - \mathbf{I}\lambda)\mathbf{x} = \mathbf{0}$

Now there are two possibilities for solutions:

- I. $\det(\mathbf{A} - \mathbf{I}\lambda) \neq 0$
 - $\Rightarrow \mathbf{x} = (\mathbf{A} - \mathbf{I}\lambda)^{-1}\mathbf{0}$
 - $\Rightarrow \mathbf{x} = \mathbf{0}$ which doesn't help us.

- **II.** $\det(\mathbf{A} - \mathbf{I}\lambda) = 0$
 - $\Rightarrow (\mathbf{A} - \mathbf{I}\lambda)$ is singular
 - $\Rightarrow (\mathbf{A} - \mathbf{I}\lambda)^{-1}$ does not exist
 - \Rightarrow we can find \mathbf{x} so that $(\mathbf{A} - \mathbf{I}\lambda)\mathbf{x} = 0$

- To solve the eigenvalue problem we take two steps:
 1. Find λ such that $(\mathbf{A} - \mathbf{I}\lambda)\mathbf{x} = 0$
 2. Find \mathbf{x} such that $(\mathbf{A} - \mathbf{I}\lambda)\mathbf{x} = 0$

- Solve an example eigenvalue problem by hand (first rewriting the problem in matrix notation) given the following ordinary differential equations

$$\begin{aligned}\frac{dy_1}{dt} &= 2y_1 + 4y_2 \\ \frac{dy_2}{dt} &= 3y_1 + y_2\end{aligned}$$

- Rewriting the ODE system as a matrix system

$$\begin{pmatrix} \frac{dy_1}{dt} \\ \frac{dy_2}{dt} \end{pmatrix} = \begin{pmatrix} 2 & 4 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \quad (2)$$

- Rewrite matrix system as eigenvalue problem

$$(\mathbf{A} - \lambda \mathbf{I}) = \begin{pmatrix} 2 - \lambda & 4 \\ 3 & 1 - \lambda \end{pmatrix} \quad (3)$$

- Step 1 and step 2 **by hand lol**

- Note that eigenvectors can be scaled, ie. if \mathbf{x} is an eigenvector then $c\mathbf{x}$ is also an eigenvector, where c is scalar. These two eigenvectors are linearly dependent.
- MATLAB returns eigenvectors in a scaling that results in normalized vectors, that is $\|\mathbf{x}\| = 1$

```
% Try the same eigenvalue problem in MATLAB  
[V,D] = eig([2 4; 3 1])  
norm(V(:,1))
```

- Computing \mathbf{A}^M for large M using direct matrix multiplication is expensive: $mO(N^3)$ for an N by N matrix \mathbf{A} .
- Alternative using the eigenvalues and eigenvectors, assuming we have all n eigenvalues and eigenvectors

$$\begin{aligned}\mathbf{A}\mathbf{x}_1 &= \lambda_1\mathbf{x}_1 \\ \mathbf{A}\mathbf{x}_2 &= \lambda_2\mathbf{x}_2 \\ &\cdot \\ &\cdot \\ &\cdot \\ \mathbf{A}\mathbf{x}_n &= \lambda_n\mathbf{x}_n\end{aligned}$$

- Put all the eigenvectors in a matrix $\mathbf{S} = (\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n)$ and all n eigenvalues in the diagonal of an n by n matrix $\mathbf{\Lambda}$ then

$$\mathbf{A}\mathbf{S} = \mathbf{S}\mathbf{\Lambda}$$

\Rightarrow

$$\mathbf{A}^1 = \mathbf{S}\mathbf{\Lambda}\mathbf{S}^{-1}$$

$$\mathbf{A}^2 = (\mathbf{S}\mathbf{\Lambda}\mathbf{S}^{-1})(\mathbf{S}\mathbf{\Lambda}\mathbf{S}^{-1}) = (\mathbf{S}\mathbf{\Lambda}^2\mathbf{S}^{-1})$$

$$\mathbf{A}^3 = (\mathbf{S}\mathbf{\Lambda}^2\mathbf{S}^{-1})(\mathbf{S}\mathbf{\Lambda}\mathbf{S}^{-1}) = (\mathbf{S}\mathbf{\Lambda}^3\mathbf{S}^{-1})$$

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$$\mathbf{A}^M = (\mathbf{S}\mathbf{\Lambda}^{M-1}\mathbf{S}^{-1})(\mathbf{S}\mathbf{\Lambda}\mathbf{S}^{-1}) = (\mathbf{S}\mathbf{\Lambda}^M\mathbf{S}^{-1})$$

- Since $\mathbf{\Lambda}$ is a diagonal matrix, we only need to take the power of the diagonal elements to get the power of the entire matrix.